

ABSTRACT

In a configuration in which a control is performed for actuating the steering cylinder 17 so that the steering angle of the front wheel 11a (steering wheel), which is detected by the steering angle detector 62, becomes a target steering angle which is set in accordance with an operational state of the steering dial 42, the target steering angle of the front wheel 11a (steering wheel), which is set in accordance with an operational state of the steering dial 42, is compared with a detected steering angle of the front wheel 11a, which is detected by the steering detector 62, and when the difference between the target steering angle and the detected steering angle is a predetermined value or higher, the traveling speed of the vehicle 10 is regulated so that the traveling speed of the vehicle 10 becomes a predetermined speed or lower.